

# Drone system for increased fire safety on open decks

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# Dependable Transport Systems

- Safety and security for autonomous systems
  - Experimental V&V, Safety & Security Assurance, ODD, Automization, Safety for AI, ...
  - Accredited functional safety & cybersecurity assessors
    - ISO 26262 (Road Vehicles – Functional safety)
    - ISO 21434 (Road vehicles – Cybersecurity Engineering)
  - Research, courses, development support
    - ISO 26262, ISO 21434
    - IEC 62443 (Industrial communication networks - Network and system security)



- Automotive, Railway, Maritime, Agriculture, Energy, ...
- Demonstrator and tool development
- Fault/attack injection
- Dependable embedded systems



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## 1. **Fire Patrol** (main use case)

- UAV flies autonomously (incl. takeoff and landing), warns bridge when critical temperatures / fires are detected

## 2. **Fire Resource Management**

- Bird's-eye view in critical situations

## 3. **(Search and Rescue Missions)**

- Search area using thermal camera

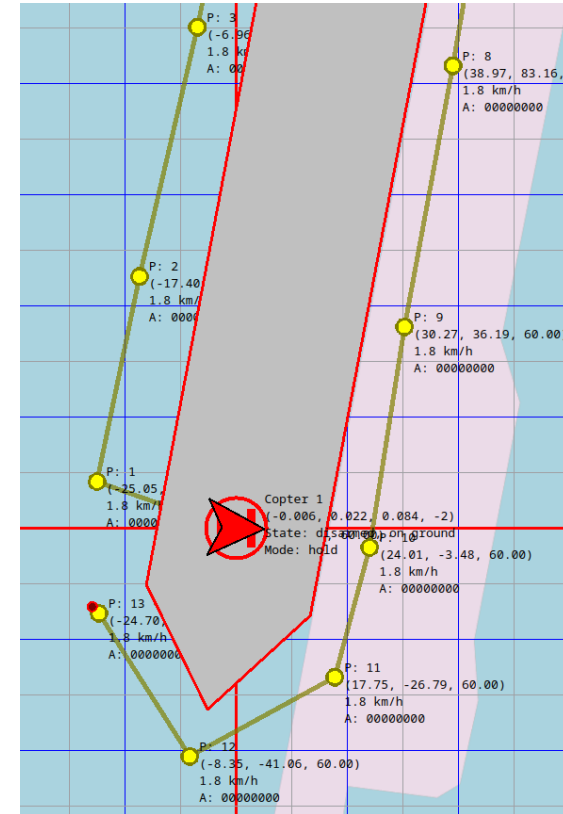
## ➤ **Assessment of**

- Technical Feasibility
- Legal Feasibility
- Usefulness



# Support Fire Prevention & Fighting

- Periodic/triggered take off
- Flight of pre-defined paths (autonomous fire rounds)
- Thermal camera live stream
  - Autonomous fire threat detection
- Autonomous landing



# Challenges – Rough Weather

- Multicopter designs used in manned aircrafts

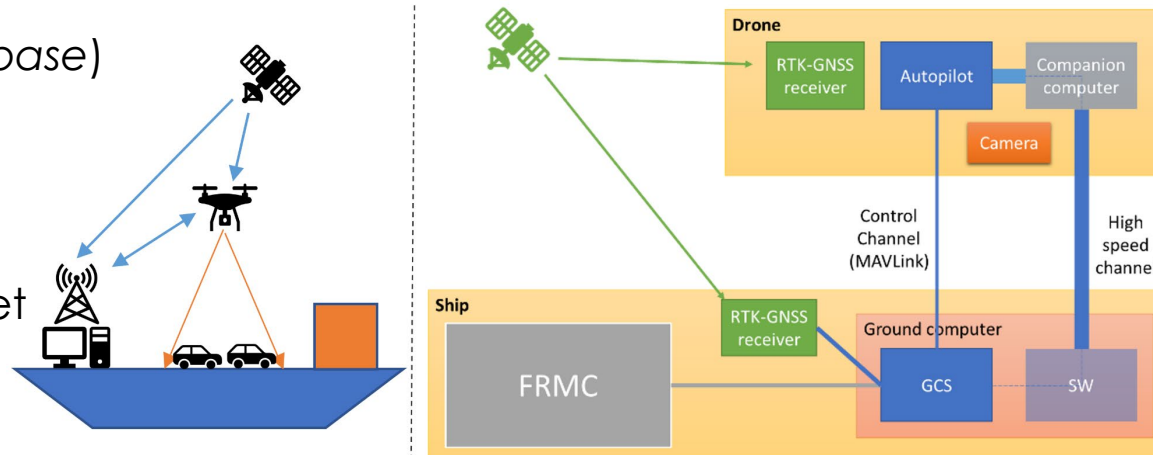
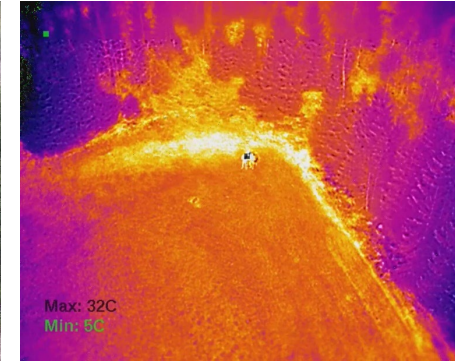


→ More cost concern than technical  
(Resistance to 50 km/h wind constant, 10mm/h rain in ca. 10k € price range)



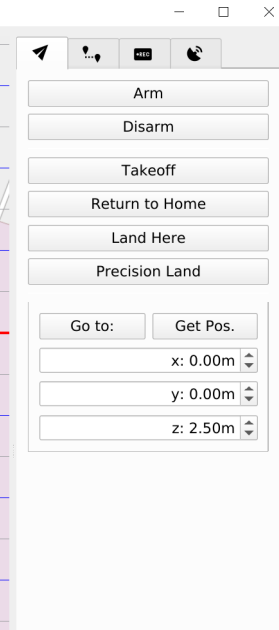
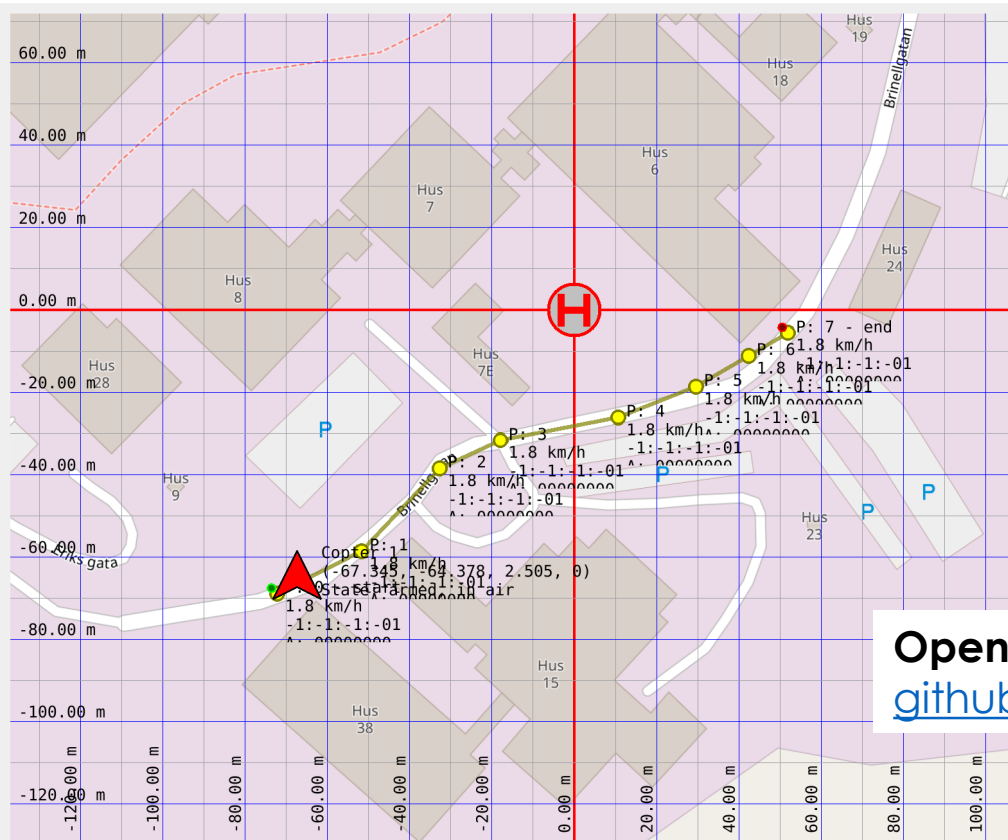
# Drone System – Overview

- **RGB & thermal** video live stream
- **Satellite-based positioning** (RTK GNSS)
- **Ground computer**
  - Implements control logic for realizing use cases
  - Position reference (*moving base*)
  - Video / sensor analysis
  - User interface
- **Out of scope: charging**
  - Solutions available on market (e.g., Skycharge Skyport)

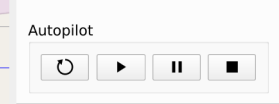


# Prototyping (1) – Control Tower

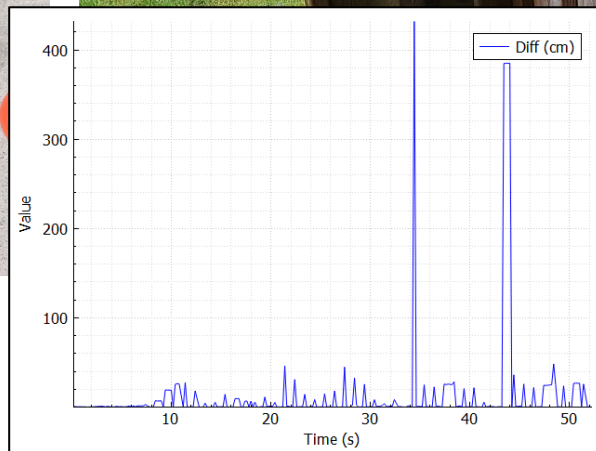
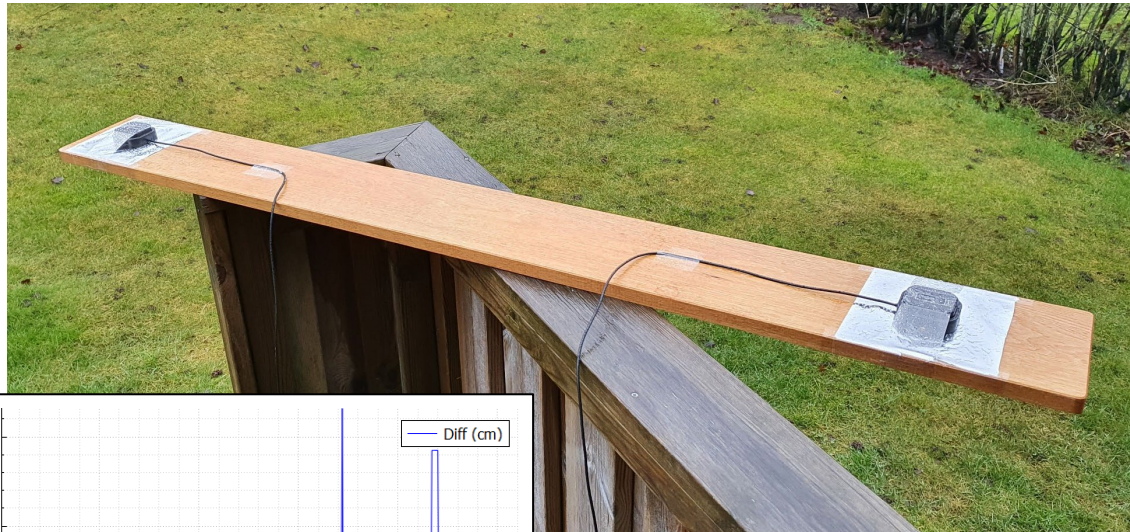
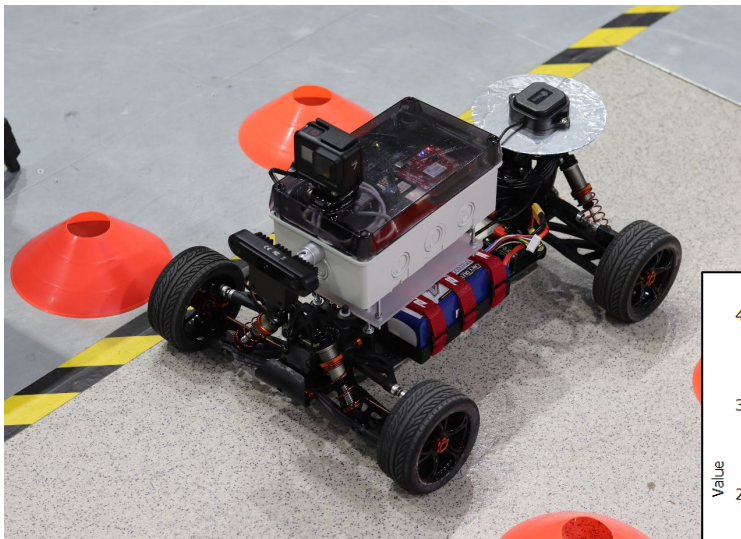
Control Tower



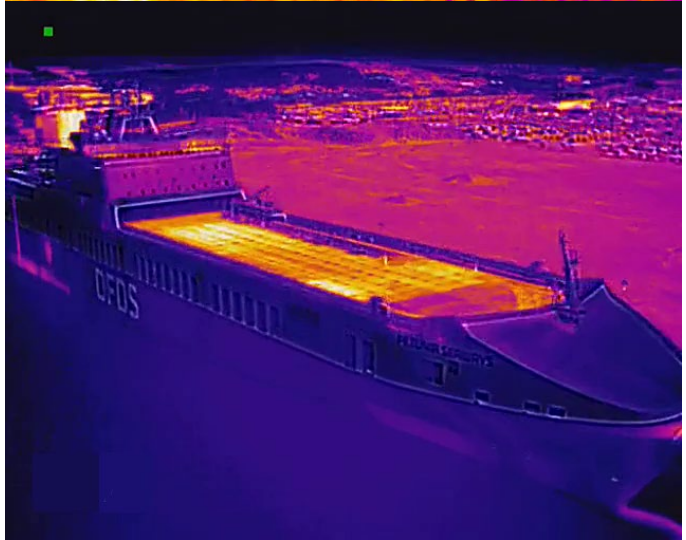
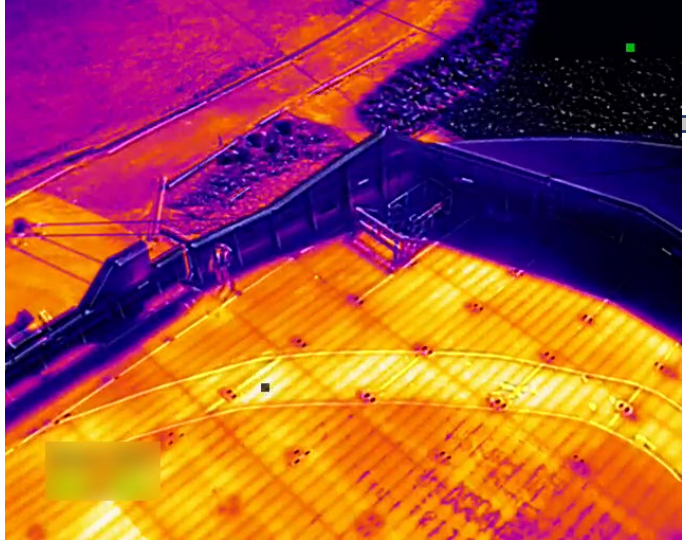
**Open source:**  
[github.com/RISE-Dependable-Transport-Systems](https://github.com/RISE-Dependable-Transport-Systems)



# Prototyping (2) – Positioning (RTK GNSS)

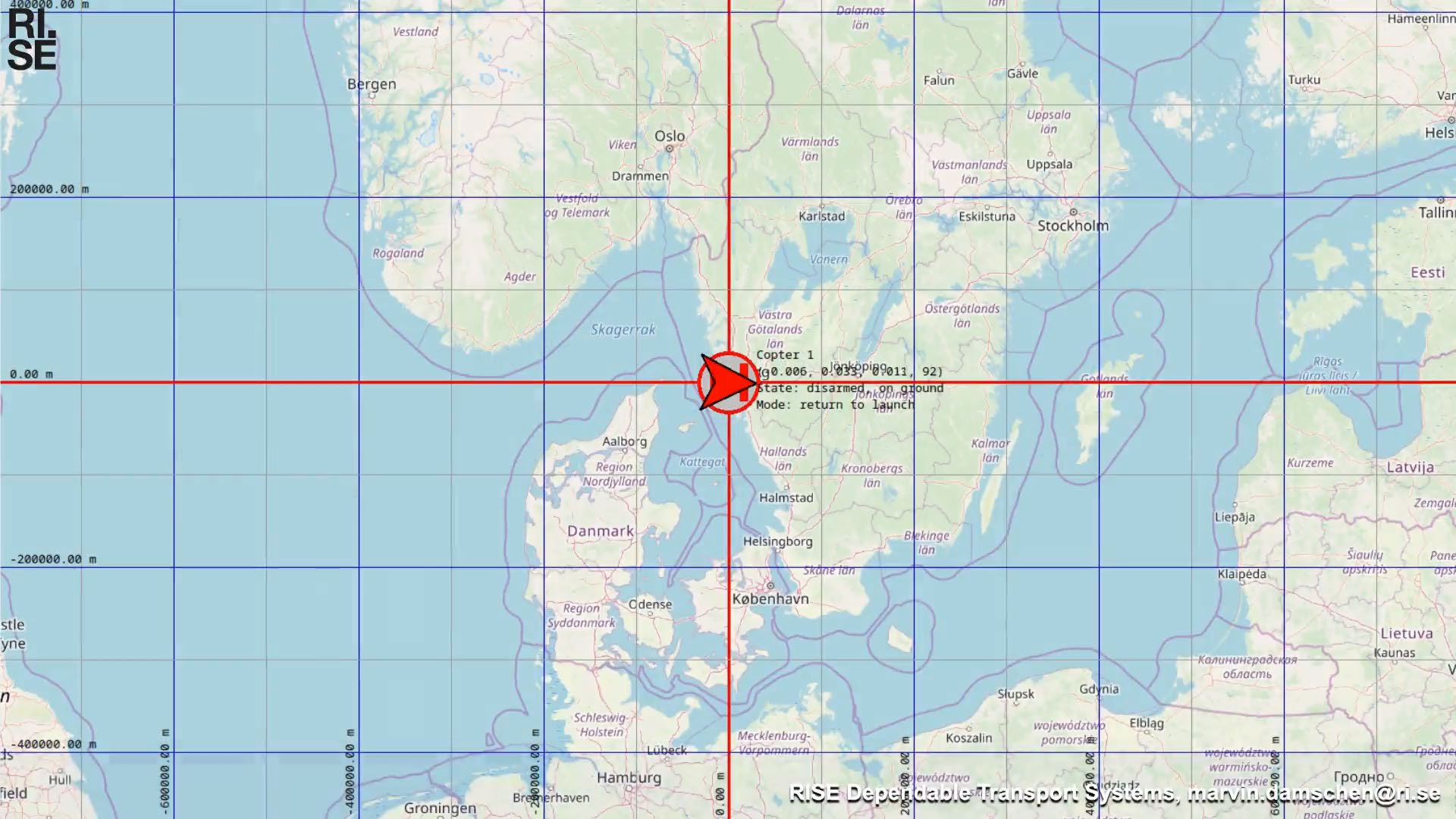








RISE



Copter 1  
(60.006, 20.035, 0.011, 92)  
State: disarmed on ground  
Mode: return to launch

# Online Questionnaire

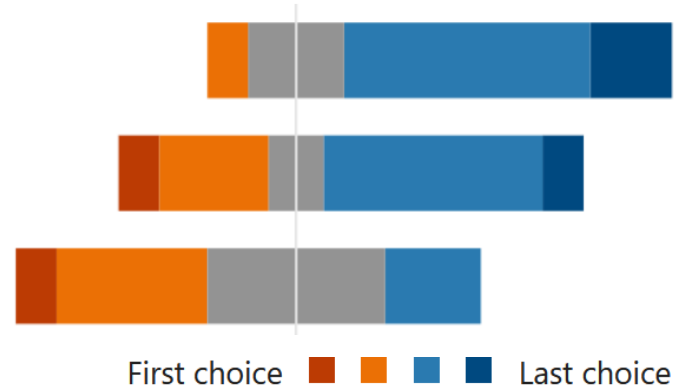
- 34 maritime experts replied to ~60 questions. Excerpt:

■ Strongly disagree   ■ Disagree   ■ Neutral   ■ Agree   ■ Strongly agree

Automated fire patrols would improve fire safety

Automated fire patrols would relieve the crew

Manual fire rounds using a handheld thermal camera would work equally well as automated fire rounds...



## Rank Options

1 Search & rescue

2 Fire patrol

3 Fire resource management

4 Other (please specify in further ...)



# Results

- **Prototype drone system designed**, built on open standards and open-source software.
- **Technical feasibility evaluated positively** overall but further development is needed.
- **Legal feasibility was assessed**: operational authorization required, best pursued in collaboration with ship operator
- **Usefulness is assessed positively**. Challenges remain in achieving a reasonable selling price and trust in system.
- **SWOT analysis** provides a concise summary for strategic business planning.

Strengths	Weaknesses
<ul style="list-style-type: none"> <li>• Provided bird's-eye view is a unique and powerful feature in various situations</li> <li>• Can speedup localising missing person, fire detection and situational understanding, thus, save lives and protect property</li> <li>• Helps avoid human error in existing procedures</li> <li>• Technically feasible with off-the-shelf components and open standards</li> <li>• Drone system maintenance could be combined with other scheduled maintenance</li> <li>• Once installed, other use cases can effectively be supported: evacuation situations, inspections, supporting ship's navigation in difficult situations, ...</li> <li>• The offshore context is quite challenging. Once "conquered", the system can further support applications along or on shore</li> </ul>	<ul style="list-style-type: none"> <li>• Requires a considerable investment</li> <li>• Regulation and integration are challenging and time-consuming</li> <li>• Introduces safety risks itself (esp. take-off and landing operations as well as charging)</li> <li>• Subject to weather, weather resistance is a cost factor</li> <li>• Monitors open decks only</li> <li>• Flight times are a limiting factor</li> <li>• High usability includes training and getting the crew used to the system. Otherwise, might be seen as a toy or distraction</li> <li>• Required manual interaction needs to be kept low, as much automation as possible</li> <li>• False alarms need to be kept at a minimum</li> </ul>
Opportunities	Threats
<ul style="list-style-type: none"> <li>• Drone technology is a fast-growing market, leading to lower required investments and better products</li> <li>• Drone servicing and repair is a fast-growing market, helping to keep OPEX low</li> <li>• Airspace regulations and management are under development, clearly specifying the integration of drone-base services</li> <li>• Maritime industry is increasingly digitized and going towards automation in general</li> </ul>	<ul style="list-style-type: none"> <li>• Revised maritime regulations (e.g., SOLAS) can strongly influence the interest of ship operators</li> <li>• Trust in the system is crucial but can be harmed by external influence and single negative events (e.g., news about an autonomous drone crashing into people)</li> </ul>



Thank you for  
your attention!

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# Full report



# Online QNR



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